DB600 SERIES

DIGITAL INDICATING CONTROLLER



The DB600 series is a digital indicating controller with the indicating accuracy of ±0.1% and the control cycle of approximately 0.1 seconds.

Various functions including universal input and multiple setting values (8 types) are provided as standard.

There are three types of size.

DB670 --- 96 x 96mm, DB650 --- 48 x 96mm,

DB630 --- 48 x 48mm

FEATURES

Excellent control performance

PID control algorithm and Z control algorithm are selectable according to the application.

PID control algorithm: Conventional control method Z control algorithm: Our new algorithm (patent with Iwate Univ.) which has evolved the PID control method. Especially, the effect can be expected such as overshoot suppression and speedy recovery in the event of disturbance control (during opening and closing of the electric furnace).

Large easy-to-view 5-digit 11 segments display

Process value (PV) and set value (SV) are displayed by large easy-to-view 5-digit display indicators. The resolution of 0.1°C is enabled for more than 1000°C.

Highly-functional operation screen and settings screen

The controller inherits the operation screen and the settings screen adopting the LCD (liquid-crystal-display) which has been familiarized for long time. Furthermore, the screens have become high-definition and highly sophisticated.

Operability inheriting previous models

The controller inherits the settings screen which has been familiarized for long time. You can set up it with operation which is not different from previous models. The performance of touching-keys has been improved and the outstanding operability has been realized.

What is Z control?

Z Control is applied from control algorithm of skunk cabbage (white arum).

Skunk cabbage is a plant that generates heat to maintain body temperature at about 20 °C in spite of changes in the outside temperature.

Incorporating system of heating control by minimum energy to the con-



Excellent control

Control algorithm (PID control, Z control)

You can choose the control algorithm PID control and Z control depending on the controlled object or application. PID control

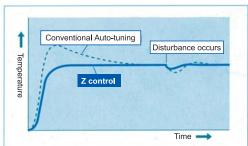
Conventional control algorithm

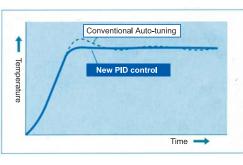
It is our original control algorithm which we evolved from general PID control.

Especailly during heating control, it can suppress overshoot effect, shortening stabilzaiton time, speed up of returing speed from distrubance (ex. the opening and closing of the oven door).

Achieve better control condition by new auto-tuning Improved conventional auto-tuning and determine more appropriate control parameter setting.

Compared to the conventional method, it can suppress overshooting and reduce of the settling time.





24V power supply voltage type available

The power supply voltage 24V (AC/DC) type, which is advantageous in respect of safety, is available.

Various operating status in one glance

Operating condition Setting value ramp (option for program model) Analog bar output

Universal input

Various measurement ranges of DC voltage (up to maximum 10V) inputs, DC current input, thermocouple inputs and resistance thermometer inputs have been built-in.

Program Operation (option)

Set 4 patterns, 12 steps. Patterns are repeatable and linkable.

Conforming to international safety standards and European directives (CE)

The controller is in conformity with European directives (CE), and is UL and c-UL approved.

Easy parameter setting

Parameters can be easily setup by using exclusive engineering cable (RZ-EC4) (sold separately) and setting software (downloadable from web site)

Easy to connect with Mitsubishi PLC, MELSEC-Q Series by using FB (function block) library

Please download the FB library from Mitsubishi Electric Corporation homepage.

MODELS **●**DB670 ●DB650 DB67 DB65 Control algorithm Control algorithm 1: PID control 1 : PID control 2 : Z control 2 : Z control Control output 1 Control output 1 ON-OFF pulse output type ON-OFF servo output type Current output type ON-OFF pulse output type ON-OFF servo output type Current output type 3: 5 SSR drive pulse output type SSR drive pulse output type Voltage output type Voltage output type Control output 2 (Option) Control output 2 (Option) 0 : None 0 : None ON-OFF pulse output type *1 3: Current output type *1 Current output type *1 Voltage output type *1 6 : Voltage output type *1 Communications interface Communications interface + 5 External signal input points + 5 External signal input points / 5 Status output points (Open collector / 5 Status output points (Open collector output (Option) 0 : None A : RS422A + 5 External signal input output) (Option) 0 : None A : RS422A + 5 External signal input points [DI 1 to 5] S: RS485 + 5 External signal input points [DI 1 to 5] RS485 + 5 External signal input points [DI 1 to 5] points [DI 1 to 5] RS422A + 5 Event output points RS422A + 5 Event output points [EV 5 to 9]*2 [EV 5 to 9]*2 C: RS485 + 5 Event output points RS485 + 5 Event output points [EV 5 to 9]*2 [EV 5 to 9]*2 Transmission signal output Transmission signal output + 2 Alram event output points + 2 Alram event output points (Mechanical relay output)(Option)*5 (Mechanical relay output)(Option)*5 0: None 4: 4 to 20mA + 2 Event output points [EV3,4] *1,*2 6: 0 to 10V + 2 Event output points [EV3,4] *1,*2 7: 2 Event output points 4 to 20mA + 2 Event output points 4: [EV3,4] *2 0 to 10V + 2 Event output points [EV3,4] *2 2 Event output points [EV3,4] *1,*2 [EV3,4]*2 Remote signal input Remote signal input + 2 External signal input points (Option) + 2 External signal input points (Option) 0 : None 5 : 4 to 20mA 0: None 4 to 20mA 7:0 to 10V 0 to 10V 8: 4 to 20mA + 2 External signal 4 to 20mA + 2 External signal input points [DI6,7] *1,*3 input points [DI6,7] *3 A: 0 to 1V + 2 External signal 0 to 1V + 2 External signal input points [DI6,7] *3 input points [DI6,7] *1,*3 B: 2 External signal input points [DI6,7] *1,*3 2 External signal input points Programming function (Option) [DI6,7] *3 Programming function (Option) - : None None P: Available P: Available 2 Alarm event output points (Mechanical relay output)+ Heater disconnection detection(Option) 2 Alarm event output points (Mechanical relay output)+ Heater disconnection detection(Option) 0 : None 2 Event output points 0: None 1: 2 Event output points [EV1,2] *2,*4 [EV1,2] *2,*4 2 Event output points 2 Event output points [EV1,2] *2,*4 [EV1,2] *2,*4 + Heater disconnection detection *5 + Heater disconnection detection *5 Additional Function (Option) Additional Function (Option) 0 : None Waterproof 0 : None Waterproof A: Output scaling Output scaling *6 Lower limit burnout *6 Lower limit burnout Square root calculation Open loop system ON-OFF servo Waterproof + Output scaling Waterproof + Lower limit burnout *6 C: Square root calculation Open loop system ON-OFF servo Waterproof + Output scaling D Waterproof + Lower limit burnout *6 Waterproof + Square root calculation Waterproof + Square root calculation H: Water proof + open loop system ON-OFF servo H: Water proof + open loop system ON-OFF servo Power voltage A: 100 to 240V AC D: 24V AC/DC Power voltage A: 100 to 240V AC D: 24V AC/DC

- *1 It can be specified when Control output 1 is "1", "3", "5" or "6".

 *2 Alarm event only functions on mechanical output so please confirm the event function.

 *3 It can be specified when 2 Event output points

 + Heater disconnection detection is "0" or "1".

 *4 When specification with Control output 2, number of event output points is only 1 point [EV2]

 *5 It can be specified when Control output 1 and Control output 2 are
 "1" or "5" and Remote signal input + 2 External signal input points is "0", "5", "6" or "7".

 However, if Control output 1 and Control output 2 are both
 "1" or "5", it can be operated with Control output 1.

 *6 Only PID control can be specified.

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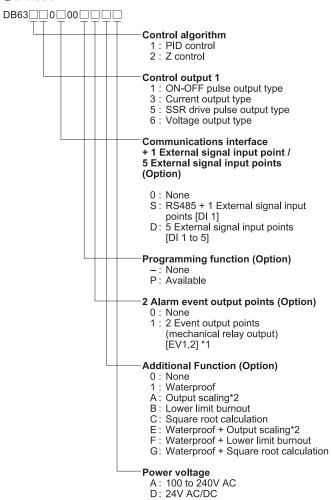
 *5 It can be specified when Control output 1 and Control output 2 are "1" or "5" and Remote signal input + 2 External signal input points is "0", "5", "6" or "7".

 However, if Control output 1 and Control output 2 are both "1" or "5", it can be operated with Control output 1.

 *6 Only PID control can be specified.



●DB630



MEASURING RANGES

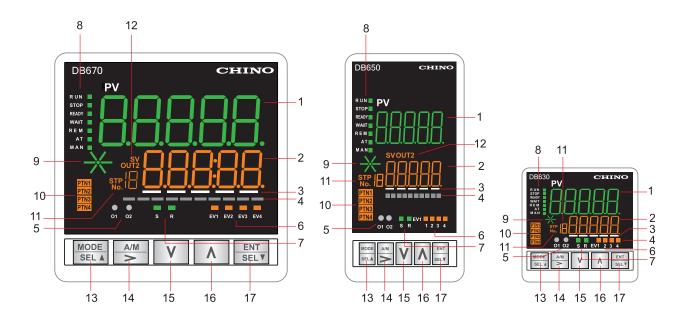
	Input type	Measuring ranges	Measuring accuracy		
	В	0.0 to 1820.0°C		Below 400°C: Out of specifications 400 to 800°C: ±0.2%FS±1digit	
	R	0.0 to 1760.0°C		Bellow 400°C: ±0.2%±FS1digit	
	S	0.0 to 1760.0°C			
	N	0.0 to 1760.0°C			
	K1	-200.0 to 1370.0°C	±0.1% of FS		
글	K2	-200.0 to 500.0°C	±1digit		
Thermocouple	Е	-200.0 to 900.0°C	For below 0°C,		
noc	J	-200.0 to 1200.0°C	±0.2% of FS		
Ë	Т	-200.0 to 400.0°C	±1digit		
) e	U	-200.0 to 400.0°C			
	L	-200.0 to 900.0°C			
	WRe5-WRe26	0.0 to 2310.0°C			
	W-WRe26	0.0 to 2310.0°C		Below 400°C: ±0.4%FS±1digit	
	Platinel II	0.0 to 1390.0°C			
	PtRh40-PtRh20	0.0 to 1880.0°C	±0.3% of FS ±1digit	Below 400°C: out of specification 400 to 800°C: ±0.8%FS±1digit	
	Au-Pt	0.0 to 1000°C	±0.1% of FS ±1digit		
	Pt100	-200.0 to 850.0°C			
_	Ft100	-200.0 to 200.0°C	±0.1% of FS		
김	JPt100	-200.0 to 649.0°C	±0.1% or F3		
	01 1100	-200.0 to 200.0°C	Tuigit		
	Pt50	-200.0 to 649.0°C			
	20mV	-20.00 to 20.00mV			
DC voltage	100mV	-100.00 to100.00mV	±0.1% of FS		
olta	5V	-5.000 to 5.000mV	±1digit		
ge	10V	-10.00 to 10.00mV			

^{*} Accuracy indicates the performance under reference operating condition.
* For thermocouple, the reference junction compensation accuracy is added to the above measured accuracy.
*To measure DC current, ranges is converted to DC voltage by optional current input reciving resistor [250 Ω]

^{*1} Alarm event only functions on mechanical output so please confirm the event function.

^{*2} Only PID control can be specified.

NAMES OF VARIOUS PARTS



Display -

- 1. Measured value (PV)/ Parameter setting title
- 2. Setting value (SV)/ operating condition/ parameter setting value
 - Displays SV, operating status (output value, occurred event, auto tuning, etc.) and parameters.
- 3. Cursor for setting parameter
- 4. Analog bar
 - Displays Output value, CT measured value, feedback measured value, step time.
- 5. Output
 - O1: Displays output value status of output 1.
 - O2: Displays output value status of output 2.*
 - *ON-OFF servo output type O1 and O2 both displays output 1 status.
 - Always OFF when it is current output type / voltage output type
- 6. Event
- 7. Communication status display
 - *Option model only
- 8. Operating status display
 - Constant value operation (program operation OFF)
 - Program operation (program operation ON)*Option model only
- 9. Setting value ramp display
 - Constant value operation (program operation OFF)
 - Program operation (program operation ON)
 - *Option model only
- 10.Pattern No. (program operation ON)
 - *Option model only
- 11 Execution No./ Step No.
 - Constant value operation (program operation OFF)
 - Program operation (program operation ON)
 - *Option model only
- 12. Operation screen display

Lights when displaying [PV/SV], [PV/OUT], [PV/OUT2]

Function keys —

- 13. [MODE] key: Depending on the screen of which key is pressed at, following screen is displayed.
 - Displays operation initial screen, when displaying operation screen expect for operation initial screen.
 - Displays initial screen of MODE0, when displaying operation initial screen of operation screen.
 - Displays operation initial screen, when displaying initial screen of setting screen.
 - Displays initial screen of setting screen, when displaying setting screen expect for initial screen.

[SELECT] key (REVERSE): Switches operation screen or MODE screen in reverse direction

[CANCEL] key: While setting/changing of parameter (dot at first digit of setting value blinks), setting/changing can be canceled. After the cancelation, dot blinking of setting value turns OFF.

- 14. [A/M] key: Switches AUTO/MAN of output 1/output 2. Operates while displaying operation screen. It cannot be operated while displaying setting screen.
 - [>] key: Moves cursor for setting parameter to the right when setting numeric value on the parameter setting screen. It cannot be operated while displaying operation screen.
- 15. [V] key: Decreases (decrement/changing of parameter) setting parameter and initial screen of each setting screen.
- 16. [\Lambda] key: Increases (increment/changing of parameter) setting parameter and initial screen of each setting screen.
- 17. [ENTER] key: Registers setting / changing parameter. After the registration, dot blinking of setting value of setting/ changing parameter turns OFF.
 - [SELECT] key: Switches operation screen and MODE screen to the forward direction.



EASY PARAMETER SETTTING

Parameters can be set easily using exclusive engineering cable (sold separately) and DB setting software (download from our homepage).

Engineering cable

USB engineering cable (RZ-EC4)



Infrared communication engineering cable (RZ-EC5)*



Since it is connected from unit front side by infrared communication, you can set the parameters in the mounted state.

*Applicable to DB650, DB670

DB600 setting software

DB600 setting software is a software that enables reading and editing the parameters directly from the unit or parameters edited and saved beforehand can be applied to the unit. Simple data acquisition is also possible.

Compatible OS Windows 7 (32bit/64bit) Japanese/English Windows 8.1 (32bit/64bit) Japanese/English Windows 10 (32bit/64bit) Japanese/English

NET Framework 4 or later has to be installed on the above OS



USEFUL COMMUNICATION INTERFACE FOR BUILDING INSTRUMENTATION SYSTEM

Communication interface (RS422A, RS485)

Able to connect to PLC via communication controller SC7D and able to load the data or set the parameters. (Option). Remote operations and parameter management using PLC is also possible.

RS422A/RS485 (In case of DB630 only RS485)

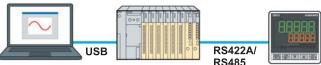


FUNCTION BLOCK PREPARED FOR EASY CONNECTION WITH PLC

DB600 series related circuit block is prepared as parts under Mistubishi Electric PLC sequence program. Supports efficiency and standardization in the development field.

Function details

Reading from DB600	PV,SV and other various setting parameters
Writing from DB600	SV and various other setting parameters



Applicable models

digital transmission

(master unit)

	Sequencer CPU unit			
Mistubishi	(high performance model, universal model)			
PLC	Serial communication unit			
MELSEC-Q	(QJ71C24N (CH2 only)), QJ71C24N-R4)			
series	Software: GX Works2			
	(Ver. 1.09K or later)			

remote

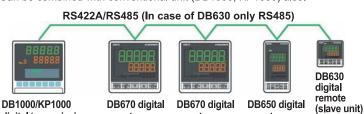
(slave unit)

Usage example

Writing execution parameters
Reading various setting parameters from multiple DB600
Writing program pattern/ selection of patterns
Indication of running operation

DIGITAL TRANSMISSION/ DIGITAL REMOTE FUNCTION

Master unit digitally transmits the SV and slave unit receives it as remote SV. Realization of no transmission error remote operation. Can be combined with conventional unit (DB1000, KP1000) also.



remote

(slave unit)

remote

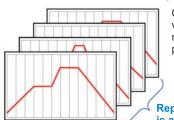
(slave unit)

Digital remote function

MODBUS	RUN/READY, PID No., SV (no decimal point)
Private	SV (with decimal point)

USEFUL FUNCTIONS

PROGRAM FUNCTION (OPTION)



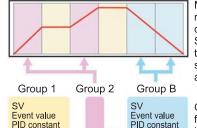
Control is performed by the preset value and required time. 1pattern max. 12 steps. Max. 4 kinds of pattern can be set.

Repetitions and linking is also possible

GROUP SETTING FUNCTION (OPTION)

Output limiter

Guarantee



Maximum of 8 groups can be registered combining main control parameter to one. Selecting the group No. at the time of running and setting the parameters in a batch is possible.

Group No. can be allocated for each step when program is running.

MULTI OUTPUT SWITCHING (OPTION*1)

Calculation result of output1 can be output to either SSR drive pulse output, current output/voltage output or ON-OFF pulse output (EV2).

Output limiter

Guarantee

*1 This function can be set when the model is as below. (Inside the \square is arbitrary)

DB65_5311
DB65 53 2 2 2
DB65 56 1 1 1
DB65 56 2 2 2
DB67 53 1 1 1
DB67 53 2 2 2
DB67_5611
DB67 56 2 2 2
11 1

Output 1: SSR drive pulse output type

Output 2: Current output or voltage output type

Mechanical relay output: 2 Alarm event output points [EV2] (+ heater disconnection detection)

Terminal output when multi output switching is set

	Setting values of multi output switching							
	Normal output setting SSR drive pulse output setting Current of		Current output/ Voltage output setting	ON-OFF pulse output setting*2				
Control output 1 terminal output	Control output 1 calculation result [MV 1]	Control output 1 calculation result [MV 1]	0% output	0% output				
Control output 2 terminal output	Control output 2 calculation result [MV 2]	0% output	Control output 1 calculation result [MV 1]	0% output				
EV2 terminal output	EV2 event judgement result	EV2 event judgement result	EV2 event judgement result	Output control output 1 calculation result [MV 1] is output by ON-OFFpulse signal				

^{*2} If it is ON-OFF pulse output type setting, then EV2 event judgment result (including heater alarm) will not be output from EV2 terminal. If using ON-OFF pulse output setting and alarm event output (including heater alarm) by DB650/DB670, please select alarm event output [EV3, EV4].

INPUT SPECIFICATIONS

Input type:

Thermocouple B, R, S, N, K, E, J, T, U, L, WRe5-WRe26, W-WRe26, Platinel II, PtRh40-PtRh20, Au-Pt

DC voltage

±20mV, ±100mV, ±5V, ±10V Resistance thermometer Pt100, JPt100, Pt50

Measuring range: Thermocouple 16 ranges, DC voltage 4 ranges,

Resistance thermometer 5 ranges

Temperature unit:

±0.1% of FS ± 1 digit of measuring range Accuracy rating:

For details, refer to "measuring ranges and

accuracy ratings"

Reference junction compensation accuracy:

±1.0°C (ambient temperature 23°C ± 10°C) ±2.0°C (temperatures other than above)

Sampling rate: Approx. 0.1 seconds

Upper limit burnout is provided as standard for Burnout:

thermocouple, resistance thermometer and DC

voltage (20mA)

Output 1 produces PV abnormal output and output 2 is fixed to 0% when burnout occurs.

Upper limit alarm event is output.

Thermocouple $1M\Omega$ or more DC voltage Approx. $1M\Omega$ Input impedance:

Allowable signal source resistance:

Thermocouple 100Ω or less DC voltage (mV) 100Ω or less DC voltage (V) 300Ω or less Allowable wire resistance:

Resistance thermometer $10\Omega/1$ wire or less (resistance of 3 wires should be equal to one

another)

Resistance thermometer measurement current:

Approx. 1mA

Maximum allowable input:

Thermocouple ±10VDC DC Voltage (mV) ±10V DC DC Voltage (V) ±20V DC Resistance thermometer ±5V DC

Maximum common mode voltage: 30VAC

130dB or more (50/60Hz)

Common mode rejection ratio: Series mode rejection ratio:

50dB or more (50/60Hz)

CONTROL SPECIFICATIONS

Control interval: Approx. 0.1 seconds

ON-OFF pulse output, ON-OFF servo output (DB650 and DB670 only), Current output, SSR Output type:

drive pulse output, Voltage output

ON-OFF pulse type:

Contact type 1a contact

Pulse cycle Approx. 1 to 180 seconds Contact capacity Resistive load 240VAC 3A Inductive load

30VDC 3A 240VAC 1.5A

30VDC 1.5A Minimum load 5VDC 10mA



ON-OFF servo output type: Contact type 1a contact

Feedback resistance 100Ω to 2KΩ Contact capacity Resistive load

240VAC 3A 30VDC 3A 240VAC 1.5A Inductive load 30VDC 1.5A

5VDC 10mA Minimum load

Current output type:

Output specification 4 to 20mA DC Load resistance 600Ω or less

SSR drive pulse output type:

Pulse cycle Approx. 1 to 180 seconds Output specification ON 12V DC ±20% (load current 21mA or less) OFF 0.8V DC or less

Voltage output type: Output specification Output resistance Load resistance

0 to 10V DC Approx. 10Ω 50KΩ or more

SETTING SPECIFICATIONS

SV related: SV 8 types for constant operation (Max. 5 digits

display), SV rate-of-change

Control relations: PID 8 kinds P 0.0 to 999.9%

I ∞ 1 to 9999 seconds D 0 to 9999 seconds

Output related: Output dead band, output reset, output limiter 8

kinds, and output rate of amount limiter

DISPLAY SPECIFICATIONS

Segment type LCD (LED backlight) Display:

GENERAL SPECIFICATIONS

Rated power voltage

100 to 240V AC 24V AC/DC

Rated power supply frequency:

50/60Hz

Maximum power consumption:

100 to 240V AC (without option) DB630 100V AC 4VA 240V AC 5VA

100V AC 4VA 240V AC 6VA 100V AC 4VA 240V AC 6VA DB650 DB670

DB630 100 to 240V AC (with option)

100V AC 5VA 240V AC 7VA 100V AC 7VA 240V AC 10VA **DB650**

DB670

100V AC 9VA 240V AC 12VA **DB630**

24V AC/DC (without option)

24V AC 3VA 24V DC 2W **DB650** 24V AC 4VA 24V DC 3W **DB670** 24V AC 4VA 24V DC 3W

24V AC/DC (with option) **DB630**

24V AC 4VA 24V DC 3W 24V AC 7VA DB650

24V DC 5W DB670 24V AC 8VA 24V DC 6W

Countermeasure against power failure:

Store setting contents in non-volatile memory. (Rewrite: 1 million times)

Insulation resistance:

Between the primary and secondary terminals $20M\Omega$ or more (500V DC)

*Primary terminal: Power terminal (100 to 240V AC) EV1 to 4 output terminals (relay output), ON-OFF pulse output terminal (relay output), ON-OFF servo output terminal

(M3,M2,M1)

Secondary terminal: Power terminal (24V AC/DC), all terminals expect primary

terminals

Withstand voltage: Between the primary and secondary terminals

1500V AC (1 minute)

Casing: Fire-retardant polycarbonate (UL94V-2)

Color: Grav

Panel mounting type Mounting:

External dimensions:

DB630 48(W) x 48(H) x 88(D)mm

Depth from panel surface is 80mm

DB650 48(W) x 96(H) x 73(D)mm

Depth from panel surface is 65mm

DB670

96(W) x 96(H) x 73(D)mm Depth from panel surface is 65mm (Without option) Approx. 120g

Weight: **DB630**

(With option) Approx. 120g (Without option) Approx. 150g (With option) Approx. 230g (Without option) Approx. 240g **DB650 DB670**

(With option) Approx. 330g

Terminal screw: M3.0

DB630 At the bottom of the case Engineering port: DB650 At the top of the case

DB670 At the top of the case

Infrared engineering port (DB650 and DB670):

Front

REFERENCE OPERATING CONDITIONS

Ambient temperature:

23°C ± 2°C Ambient humidity: 55%RH ± 5% (no condensation) Power voltage: 100VAC ± 1%, 24V DC ± 1%

Power supply frequency

50/60Hz ± 0.5%

Mounting orientation:

Backward / forward ±3°, laterally ±3° Installation height:2000m or below

Vibration: 0m/s^2

Shock: 0m/s2 Installation condition:

Single panel mounting (space required around)

Wind: None

External noise: None

Warm up time: At least 30 minutes

NORMAL OPERATING CONDITIONS

Ambient temperature:

-10°C to 50°C (-10°C to 40°C for close

installation)

Maximum ambient humidity (ambient temperature -10 to 31°C):

90%RH (no condensation)

Maximum ambient humidity (ambient temperature 31 to 50°C):
90 to 50%RH (no condensation)

*Decreases linearly from 90% RH at 31°C, or to

50% RH at 50°C.

Minimum ambient humidity: 20%RH

Power voltage: 100 to 240V AC 90 to 264V AC

24V AC/DC 21.6 to 26.4V AC/DC

Power supply frequency

50/60Hz ± 2%

Mounting orientation:

Backward/forward ±10°, laterally ±10° Installation height: 2000m or below

Vibration: 0m/s^2 Shock: 0m/s^2 Installation condition:

Panel mounting (space above and below)

External noise: None

Ambient temperature variation ratio: 10°C/hour or less

TRANSPORT CONDITIONS

Ambient temperature:

-20°C to 60°C

Ambient humidity:5 to 95%RH (no condensation) Vibration: 4.9m/s² or less (10 to 60Hz)

392m/s2 or less (under factory packing Shock:

condition)

STORAGE CONDITIONS

Ambient temperature:

-20°C to 60°C *10 to 30°C for long-term storage Ambient humidity: 5 to 95%RH (no condensation)

Vibration: 0m/s^2

Shock: 0m/s² (under factory packing condition)

STANDARD

Safety:

EN61010-1, EN61020-030 (CE marking) UL61010-1, UL61010-2030 (UL) CAN/CSA C22.2 No.61010-1(c-UL) Setup category: CAT.II, pollution degree: 2

EMC compliant:

CE marking EN61326-1 ClassA Table2

*Indication or output value varies by the amount equivalent to ±10% of FS or ±2mV, whichever is

larger, during testing.

Environment regulation:

RoHS directive

OPTIONS

Programing function

4 patterns (Max. 9,999 times repeatable) Patterns:

12 steps /1pattern Steps:

Target value --- Input scale range Step setup range:

Ramp rate --- -99.999 to 99.999

Time --- 0 to 999 hours 59 minutes or 0 to 999

minutes 59 seconds

Select either PV start or SV start (arbitrary value Start temperature:

End output: Select either constant value control (setting: -5 to

105%)

Event function

No. of events	EV1 to 4 (Mechanical relay)	EV5 to 9 (Open collector)
Event that can be allotted	Alarm event Status event	Status event
Output points	Max. 4 points	Max. 5 points
Contact capacity (Mechanical relay output)	Resistance load: 240V AC3A/ 300 VDC 3A Inductive load:	24V DC 50mA
Output capacity (open collector output)	240V AC 1.5A/ 30V DC 1.5A Minimum load: 5V DC 10mA	

Alarm event: Absolute value alarm, deviation alarm, absolute value deviation alarm, set point alarm, output

value alarm, heater disconnection alarm (only when control output 1 or 2 is ON-OFF pulse output or SSR drive pulse output), Timer1, Timer2, FAIL

Status event:

Constant value operation RUN, preset manual, remote input, SV rising, SV falling, program operation (step switching, step 1 to 12, RUN, STOP, ADVANCE, RESET, END, SV hold)

Transmission signal output

Output point: 1 point

4 to 20mA DC (load resistance 400Ω or less) 0 to 10V DC (load resistance $50k\Omega$ or more) Output signal:

Accuracy: ±0.3% of full scale Output updating interval:

Approx. 0.1 seconds

Insulation: Non-isolated between the adjustment output 1

and 2

(ON-OFF pulse output type excluded)

External signal input

Input point:

DB630 5 points maximum, COM shared DB650 7 points maximum, COM shared DB670 7 points maximum, COM shared

Non voltage contact Input signal:

External contact capacity:
5V DC 2mA

Constant value operation RUN/READY switch, Function:

AUTO/MAN switch, preset manual, timer 1, timer 2, alarm event reset, execution No. selection, program/constant value operation switch, program operation RUN/STOP switch, program operation ADVANCE, program operation RESET,

program pattern selection

Remote signal input

Input point: 1 point

4 to 20mA DC (Input impedance Approx. 50Ω) 0 to 10V DC (Input impedance Approx. $100k\Omega$) Input signal:

Maximum allowable input:

DC current +30mA or less ±1.5V DC or less DC voltage ±20V DC or less ±0.3% of full scale ± 1digit

Accuracy: Approx. 0.1 seconds Sampling rate:

External signal switch:

R/L (Remote/Local)

Communications interface

com.point: 1 port

DB630 RS485 Type:

DB650 RS422A,RS485

DB670

Protocol: MODBUS-RTU, MODBUS-ASCII, Private (used for digital transmission/digital remote input) Host communication/digital transmission/ Function:

digital remote input

Z control algorithm

Our original control algorithm. Compatible of both suppressing overshoot effect and response time of returning back from disturbance. Parameter setting is same as conventional PID setting.

2 output specification

ON-OFF pulse output type, current output type, Output type:

and voltage output type. Any combination is

possible.

Insulation: Not insulated between the 2 outputs (except ON-

OFF pulse type) PID type, split type

Heater disconnection detection

Measures heater current using an external current transformer (CT)

to detect disconnection. Input points: 1 point

Control method:

CT Input range: 0.0 to 65.0mA AC (50/60Hz)

Heater current measuring range: 5.0 To 50.0A AC Input signal: 5.0 To 50.0A (50 / 60Hz)

Accuracy: ±5.0% of FS ±1digit *Designated CT: Manufactured by U.R.D.Co, LTD. "CTL-6-S-H"

LTA-P207 (800 turns, hole diameter 5.8mm), sold separately Open loop type ON-OFF servo output

Time control without using control motor feedback resistor when it is ON-Off servo output

Output scaling (Only PID control can be specified)

Scales the control output.

Lower limit burnout

When it is burnout, PV display will off scale to lower limit and lower limit alarm will be output

Square root calculation

Calculates square root for liner input

Damp proof coating

Damp proofing coating to the internal PCB

Water proofing

Attach to panel to have "IP54 equivalent" water proofing

°F value calculation

Calculates the PV and SV in °F

Accessories (sold separately)

Terminal cover (model DB630/RZ-TC2, DB650/RZ-TC3, DB670/RZ-TC3)

Attach to the back side to protect the terminals

Front protection cover (model DB630/RZ-PC2, DB650/RZ-PC3, DB670/RZ-PC4)

Attach to the front side to prevent incorrect operations

Current input receiving resistors 250Ω (model EZ-RX250)

Used at the time of direct current input (4 To 20mA)

Contact protection element (model CX-CR1 for light load, CX-CR2 for heavy load)

Attach to relay output terminal of ON-OFF output pulse and ON-OFF servo output type to protect the relay contact from noise.

USB engineering cable (model RZ-EC4)

For connecting to PC and setting parameters using DB600 software

Infrared communication engineering cable (model RZ-EC5, DB650/670 only)

Cable for infrared communication from the front side of the unit to PC. Parameters can be set by using DB600 software

Current transformer dia. 5.8 mm (for 50A) (model LTA-P207)

Designated current transformer used for heater disconnection detection. Manufactured by U.R.D.Co, LTD. "CTL-6-S-H"



■ TERMINAL ARRANGEMENT

DB670

	[13]	25	37
2	14	26	[38]
3		27	(39)
4		28	40
5		29	41
6		30	42
		31	
8		32	
9		33	
(10)		34	
		35	
12	24	36	

				1						
1	Measuring	input +	13	Communication RDA	SA	25	EV3		37	Servo M3
2	Measuring	input A+	14	Communication RDB	SB	26	EV3 C	OM	38	Servo M2
3	Measuring	input B+	15	Communication SDA		27	EV4		39	Servo M1
4	Measuring	input b	16	Communication SDB		28	EV4 C	ОМ	40	Servo R1
5	5 Control output 1+		17	Communication SG	sg	29	Transm output	nission +	41	Servo RC
6	Control out	put 1-	18	R/L(digital)DI		30	Transmission output -		42	Servo R2
7	Control output 2+	EV1	19	DI1	EV5	31	Remote	input +		
8	Control output 2-	EV1 COM	20	DI2	EV6	32	Remote	input -		
9	9 EV2		21	DI3	EV7	33	R/L(ana	alog)DI		
10	EV2 COM		22	DI4	EV8	34 CT DI6				
11	Power L		23	DI5	EV9 35 CT DI7					
12	Power N/-		-	R/L & DI COM	R/L & EV COM	-	_	I COM		
						_			1	

DB650

F		_
	13	25
	14	26
3	15	27
4	16	28
(5)	17	29
(6)	18	(30)
	19	(31)
8	20	(32)
9	21	(33)
10	22	(34)
10	23	35
12	24	36
		_

1	Measuring	input +	13	Communication RDA	SA	25	EV3		Servo M3
2	Measuring	input A+	14	Communication RDB	SB	26	EV3 C	OM	Servo M2
3	Measuring	input B+	15	Communication SDA		27	EV4		Servo M1
4	Measuring	input b	16	Communication SDB		28	EV4 C	OM	Servo R1
5	Control output 1+ 17 Communication		Communication SG	SG	29	Transmission output + Serve		Servo RC	
6	Control out	put 1-	18	R/L(digital)DI		30	Transm output		Servo R2
7	Control output 2+	EV1	19	DI1	EV5	31	Remote	input +	Transmission output +
8	Control output 2-	EV1 COM	20	DI2	EV6	32	Remote	input -	Transmission output -
9	EV2		21	DI3	EV7	33	R/L(ana	log)DI	Remote input +
10	EV2 COM		22	D I 4		_	CT T	D i 6	Remote input +
11	Power L/-		23	D I 5	EV9	35	CT	DI7	R/L(analog)DI
12	Power N/-			R/L & DI COM	R/L & EV COM	36	R/L & D	COM	R/L COM

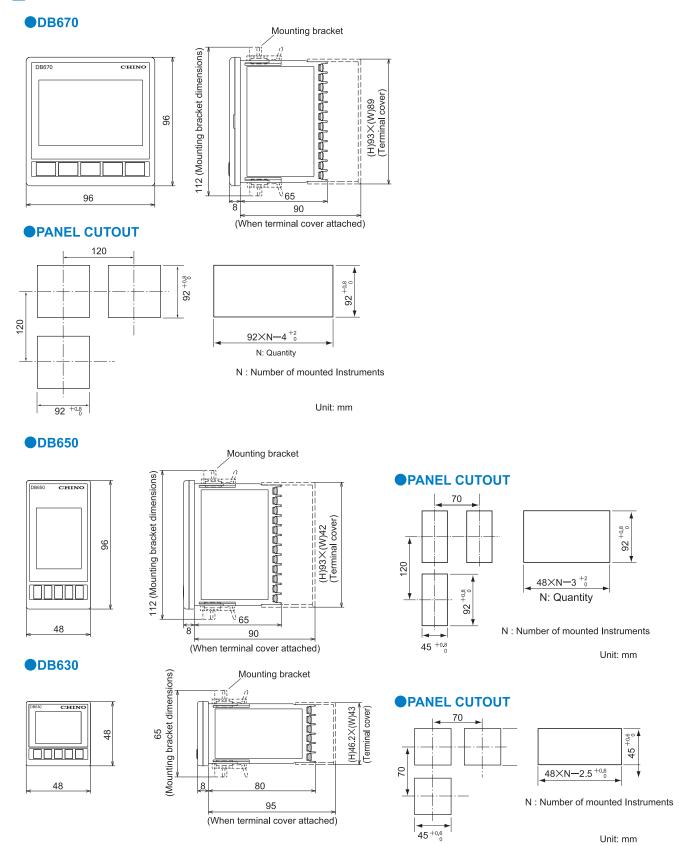
●DB630

		13
2	8	14
	9	15
	10	16
[5]		
(6)	12	

1	Control output 1+	7	Communication SA	DI1	EV5	13	Control output 2+
2	Control output 1-	8	Communication SB	D l 2	EV6	14	Control output 2- EV1 COM
3	Measuring input +	9	Communication SG	DI3	EV7	15	EV2
4	Measuring input A+	10	R/L(digital)	D i 4	EV8	16	EV2 COM
5	Measuring input B+	11	DI1	DI5	EV9	17	Power L/-
6	Measuring input b	12	R/L & DI COM	DI COM	EV COM	18	Power N/-



EXTENAL DIMENSIONS



Specifications subject to change without notice. Printed in Japan (I) 2019. 11

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